

CONGRESO INTERNACIONAL DE
**V DISEÑO E
INGENIERÍA
NAVAL**

Marzo 15 - 17 de 2017



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Departamento Administrativo de Ciencia, Tecnología e Innovación



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On the use of time-domain simulation in the design of Remotely Operated Vehicles

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MARIN

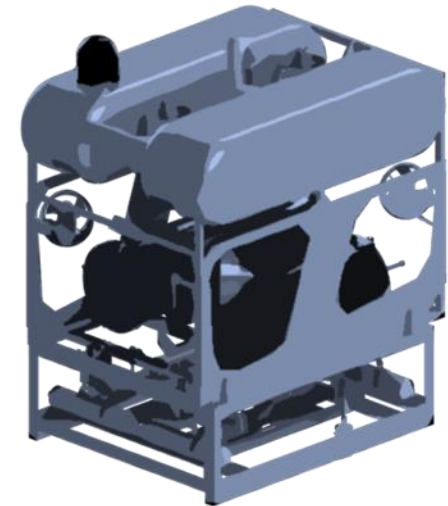
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Visor3



CONTEXT: THE PROJECT

Name:

Strategic Program for the Development of Robotic Technology for Offshore Exploration of the Colombian Sea Bed

Main goal:

To develop a robotic system including an ROV and its auxiliary systems, for assisting offshore exploration tasks

Purposes:

Increase innovation and technology development capacities through qualification of students and researchers on topics related to underwater robotics.

Support M.Sc. and Ph.D. theses on underwater robotics related subjects.

OUR CURRENT QUESTIONS

- How to conduct the design process?
- How to plan the mission?
- How to solve engineering specifics?

THIS PAPER'S QUESTIONS

- How to use time-domain simulation (TDS) as a tool during the design process?
- What questions could TDS answer?
- What simulation scenarios are relevant?

DESIGN PROBLEM

- Focus on questions about the propulsion system after component distribution information is available, aiming to evaluate operational envelope.
- Test different propeller parameters and thrusters spatial configuration.
- Evaluate efficiency, power consumption, and operating speed.

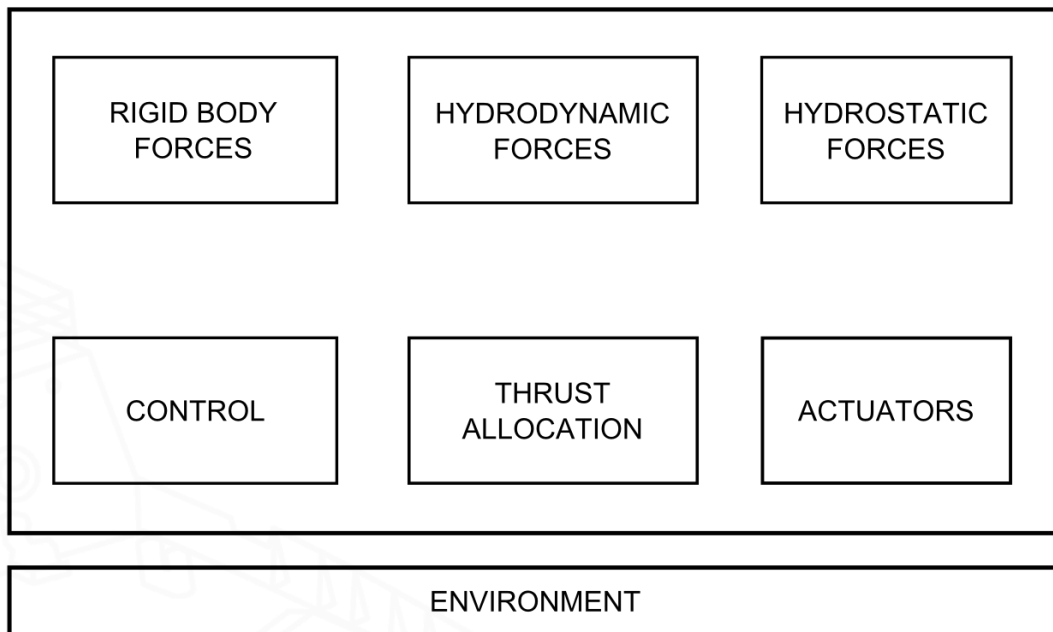
COOPERATION WITH MARIN

- MARIN: Maritime Research Institute Netherlands
 - Location (main): Wageningen, The Netherlands
 - Founded: 1929
 - Business units: Offshore, Ships, Maritime Simulation & Software Group, Nautical Centre, R&D, and Trials and Monitoring
 - Web: marin.nl
- Cooperation since 2015:
 - 2 tools: ReFRESCO CFD and aNySIM TDS codes
 - 1 internship
 - 3 papers (including this work)

- Time-domain simulation software based on rigid body dynamics.
- To study time-domain transient behavior such as dynamic response and control.
- Object-oriented programming.

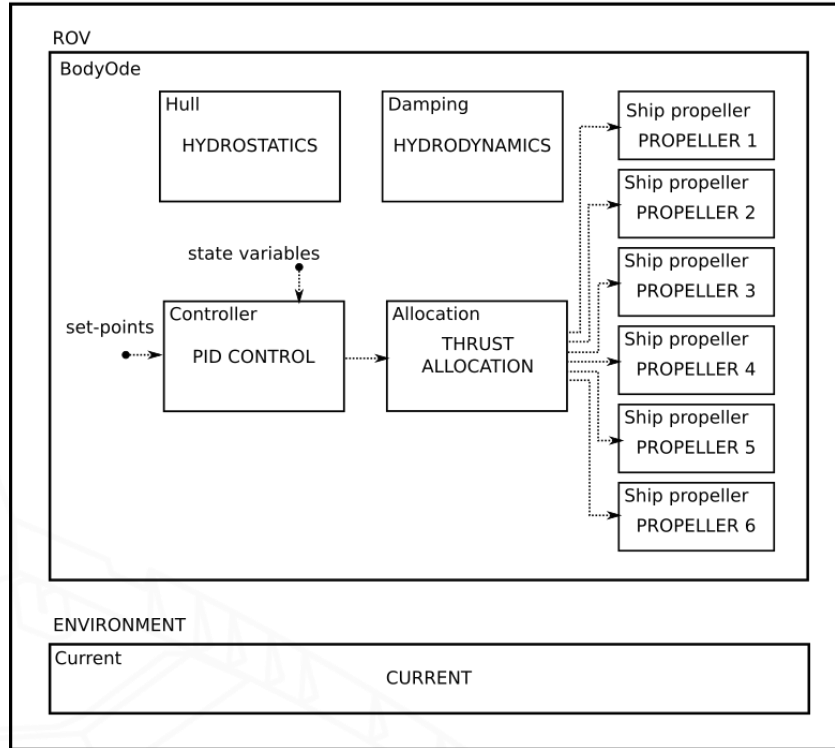
SIMULATION FRAMEWORK

ROV



SIMULATION FRAMEWORK

Scenario

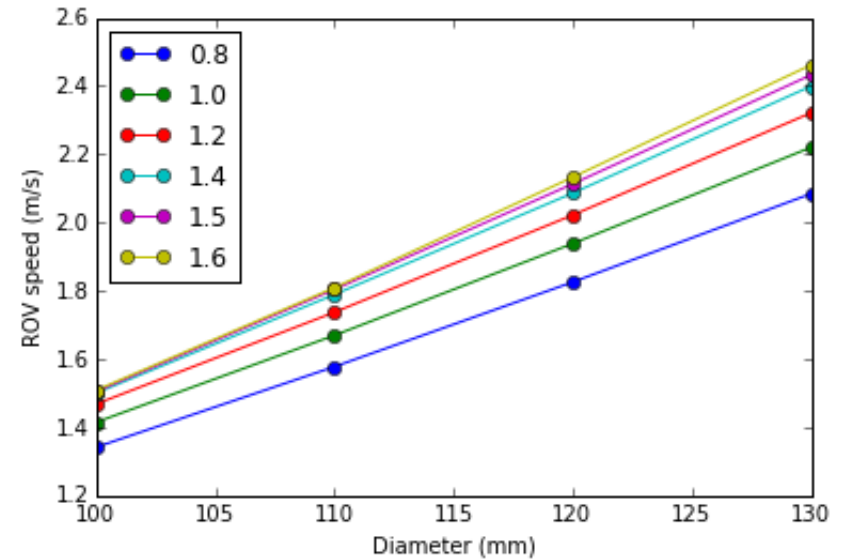
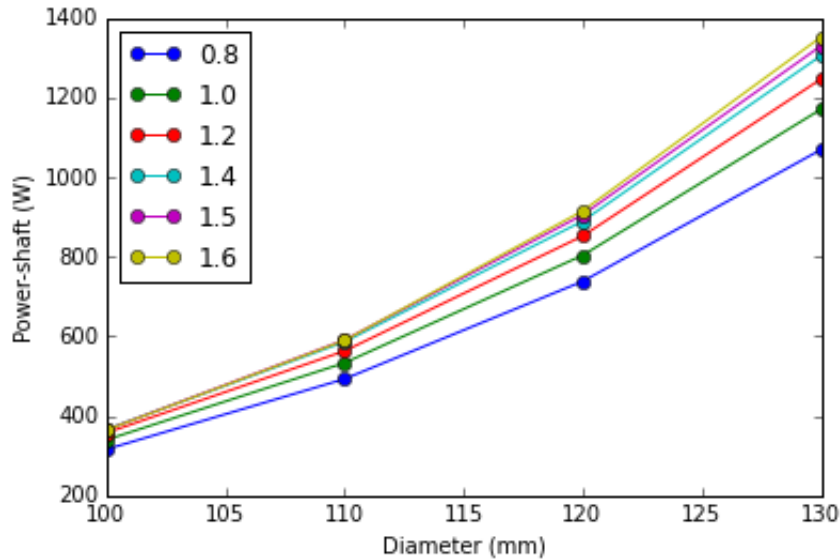


SIMULATION SCENARIOS

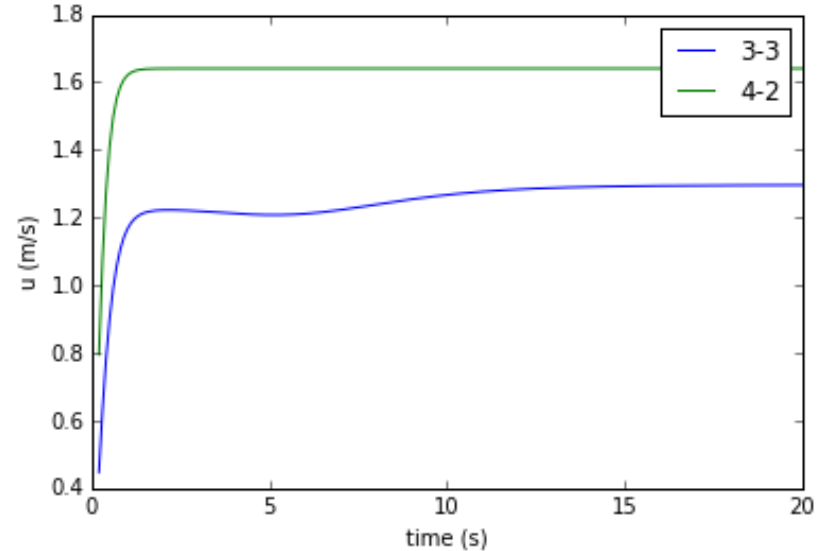
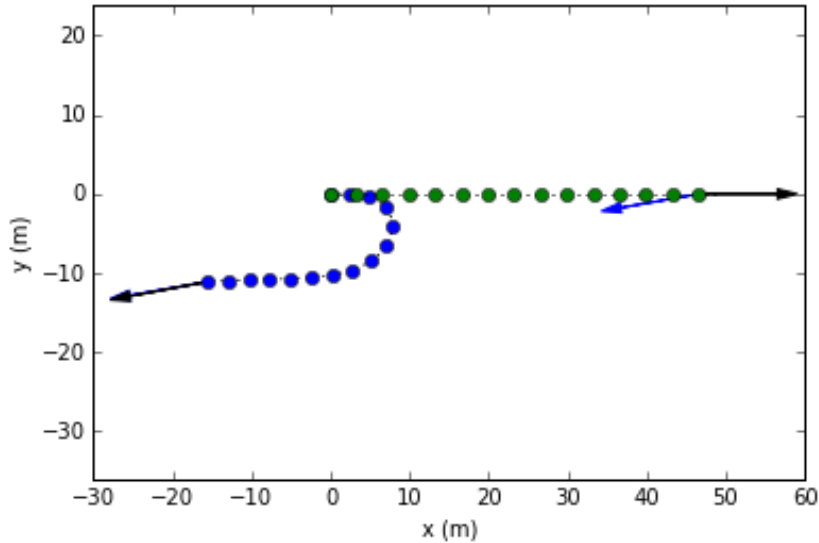
Evaluate full thrust and test the performance of the ROV in terms of efficiency, power consumption, and operation speed.

- Propeller parameters: diameter, pitch-diameter ratio, and number of blades.
- Propeller configuration:
 1. three thrusters for horizontal and three for vertical motion, and
 2. four thrusters for horizontal and two for vertical motion.

RESULTS - PROPELLER



RESULTS – THRUSTER CONFIGURATION



CONCLUSIONS

- Use of a multibody time-domain simulation tool aNySIM for the design process of an ROV was addressed.
- Different scenarios to evaluate full thrust in different directions in order to test the performance of the ROV in terms of efficiency, power consumption, and operation speed were considered.
- The proposed scenarios allowed the designers to evaluate different design propeller parameters, as well as different propeller configurations.
- Time-domain simulation seems and adequate tool for assisting the design process.

FURTHER ISSUES

- Modeling challenges such as hydrodynamic and cable induced loads.
- What the performance indices should be?
- What the simulation scenarios should be?
- What optimization problems are feasible to solve?



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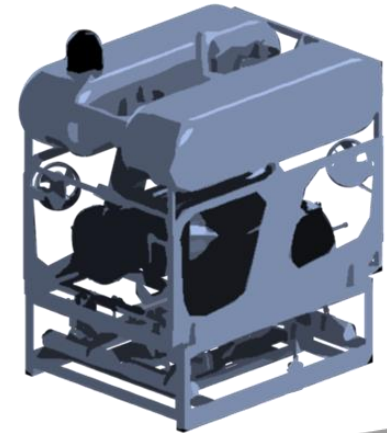
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¡THANKS! ¿QUESTIONS?

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